

# 2.9 inch E-paper Display Series WAA0290A2ADA8NXXX000



# **Product Specifications**

Customer	Standard
Description	2.9" E-PAPER DISPLAY
Model Name	WAA0290A2ADA8NXXX000
Date	2024/09/26
Revision	1.0

Design Engineering			
Approval	Check	Design	



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# **REVISION HISTORY**

Rev	Date	Item	Page	Remark
1.0	SEP.26.2024	New Creation	ALL	



#### 1. Over View

WAA0290A2ADA8NXXX000 is an Active Matrix Electrophoretic Display (AM EPD), with interface and a reference system design. The display is capable to display images at 1-bit white, black full display capabilities. The 2.9 inch active area contains 296×128 pixels. The module is a TFT-array driving electrophoresis display, with integrated circuits including gate driver, source driver, MCU interface, timing controller, oscillator, DC-DC, SRAM, LUT, VCOM. Module can be used in portable electronic devices, such as Electronic Shelf Label (ESL) System.

#### 2.Features

296×128 pixels display

High cntrast High reflectance

Ultra wide viewing angle Ultra low power consumption

Pure reflective mode

Bi-stable display

Commercial temperature range

Landscape portrait modes

Hard-coat antiglare display surface

Ultra Low current deep sleep mode

On chip display RAM

Waveform can stored in On-chip OTP or written by MCU

Serial peripheral interface available

On-chip oscillator

On-chip booster and regulator control for generating VCOM, Gate and Source driving voltage

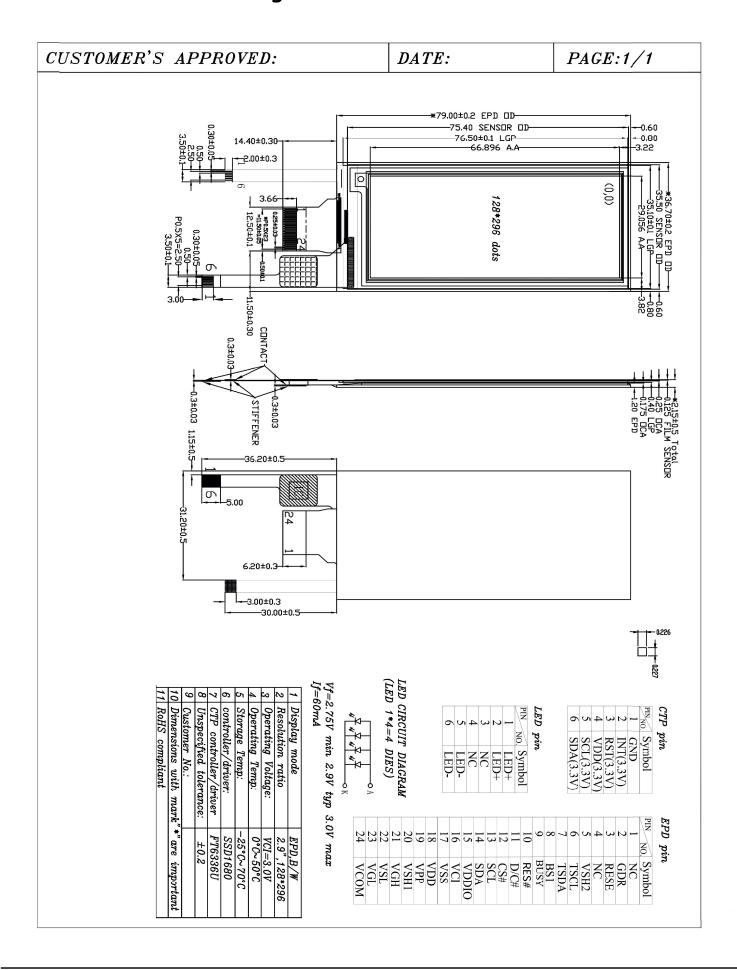
I2C signal master interface to read external temperature sensor Built-in temperature sensor

# 3. Mechanical Specifications

Parameter	Specifications Unit		Remark
Screen Size	2.9	Inch	
Display Resolution	296 (H)×128(V) Pixel		Dpi:112
Active Area	29.056(H)×66.896(V)	mm	
Pixel Pitch	0.227×0.226 mm		
Pixel Configuration	Rectangle		
Outline Dimension	36.7(H)×79.0(V) ×1.2(D)	mm	
Weight	5.5±0.5	g	



### 4. Mechanical Drawing of EPD module





# 5. Input /Output Pin Assignment

No.	Name	I/O	Description	Remark		
1	NC		Do not connect with other NC pins	Keep Open		
2	GDR	О	N-Channel MOSFET Gate Drive Control			
3	RESE	I	Current Sense Input for the Control Loop			
4	NC	NC	Do not connect with other NC pins	Keep Open		
5	VSH2	С	Positive Source driving voltage(Red)			
6	TSCL	О	I <sup>2</sup> C Interface to digital temperature sensor Clock pin			
7	TSDA	I/O	I <sup>2</sup> C Interface to digital temperature sensor Data pin			
8	BS1	I	Bus Interface selection pin	Note 5-5		
9	BUSY	О	Busy state output pin	Note 5-4		
10	RES#	I	Reset signal input. Active Low.	Note 5-3		
11	D/C#	I	Data /Command control pin	Note 5-2		
12	CS#	I	Chip select input pin	Note 5-1		
13	SCL	I	Serial Clock pin (SPI)			
14	SDA	I/O	Serial Data pin (SPI)			
15	VDDIO	P	Power Supply for interface logic pins It should be connected with VCI			
16	VCI	P	Power Supply for the chip			
17	VSS	P	Ground			
18	VDD	С	Core logic power pin VDD can be regulated internally from VCI. A capacitor should be onnected between VDD and VSS			
19	VPP	P	FOR TEST			
20	VSH1	С	Positive Source driving voltage			
21	VGH	С	Power Supply pin for Positive Gate driving voltage and VSH1			
22	VSL	C	Negative Source driving voltage			
23	VGL	C	Power Supply pin for Negative Gate driving voltage VCOM and VSL			
24	VCOM	C	VCOM driving voltage			

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I = Input Pin, O = Output Pin, I/O = Bi-directional Pin (Input/output), P = Power Pin, C = Capacitor Pin

**Note 5-1:** This pin (CS#) is the chip select input connecting to the MCU. The chip is enabled for MCU

communication only when CS# is pulled LOW.

**Note 5-2:** This pin is (D/C#) Data/Command control pin connecting to the MCU in 4-wire SPI mode. When

the pin is pulled HIGH, the data at SDA will be interpreted as data. When the pin is pulled LOW, the data at SDA will be interpreted as command.

Note 5-3: This pin (RES#) is reset signal input. The Reset is active low.

**Note 5-4:** This pin is Busy state output pin. When Busy is High, the operation of chip should not be interrupted, command should not be sent. The chip would put Busy pin High when –Outputting display waveform -Communicating with digital temperature sensor

**Note 5-5:** Bus interface selection pin

BS1 State	MCU Interface
L	4-lines serial peripheral interface(SPI) - 8 bits SPI
Н	3- lines serial peripheral interface(SPI) - 9 bits SPI

# 6. Electrical Characteristics6.1 Absolute Maximum Rating

Parameter	Symbol	Rating	Unit
Logic supply voltage	VCI	-0.5 to +4.0	V
Logic Input voltage	VIN	-0.5 to VCI +0.5	V
Logic Output voltage	VOUT	-0.5 to VCI +0.5	V
Operating Temp range	TOPR	0 to +50	° C
Storage Temp range	TSTG	-25 to+70	° C
Optimal Storage Temp	TSTGo	23±2	° C
Optimal Storage Humidity	HSTGo	55±10	%RH

#### Note:

Maximum ratings are those values beyond which damages to the device may occur. Functional operation should be restricted to the limits in the Panel DC Characteristics tables.

#### 6.2 Panel DC Characteristics

The following specifications apply for: VSS=0V, VCI=3.0V, TOPR =25°C.



Parameter	Symbol	Conditions	Applica ble pin	Min.	Тур.	Max	Units
Single ground	V <sub>SS</sub>	-		-	0	-	V
Logic supply voltage	$V_{\rm CI}$	-	VCI	2.2	3.0	3.7	V
Core logic voltage	$V_{ m DD}$		VDD	1.7	1.8	1.9	V
High level input voltage	$V_{\mathrm{IH}}$	-		0.8 V <sub>CI</sub>		-	V
Low level input voltage	V <sub>IL</sub>	-		-		0.2 V <sub>CI</sub>	V
High level output voltage	V <sub>OH</sub>	IOH = - 100uA		0.9 VCI	9	-	V
Low level output voltage	$V_{\mathrm{OL}}$	IOL = 100uA				$0.1~\mathrm{V_{CI}}$	V
Typical power	$P_{TYP}$	$V_{CI}=3.0V$					mW
Deep sleep mode	P <sub>STPY</sub>	$V_{CI} = 3.0 V$			0.003		mW
Typical operating current	Iopr_V <sub>CI</sub>	$V_{CI} = 3.0 V$		-	3.0		mA
Full update time		25 °C			3		sec
Fast update time	-	25 °C			1.5		sec
Partial refresh time		25 °C			0.3		sec
Sleep mode current	Islp_V <sub>CI</sub>	DC/DC off No clock No input load Ram data retain	-	-	20		uA
Deep sleep mode current	Idslp_V <sub>CI</sub>	DC/DC off No clock No input load Ram data not retain	-	-	1	5	uA

#### Notes:

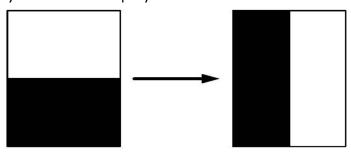
- 1) Refresh time: the time it takes for the whole process from the screen change to the screen stabilization.
- 2) The difference between different refresh methods:

Full refresh: The screen will flicker several times during the refresh process;

Fast Refresh: The screen will flash once during the refresh process; Partial refresh: The screen does not flicker during the refresh process.

During the fast refresh or partial refresh of the electronic paper, it is recommended to add a full-screen refresh after 5 consecutive operations to reduce the accumulation of afterimages on the screen.

- 1. The typical power is measured with following transition from horizontal 2 scale pattern to vertical 2 scale pattern.
- 2. The deep sleep power is the consumed power when the panel controller is in deep sleep mode.
- 3. The listed electrical/optical characteristics are only guaranteed under the controller & waveform provided by WINSTAR Display.



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#### 6.3 Panel AC Characteristics

#### 6.3.1 MCU Interface Selection

The pin assignment at different interface mode is summarized in Table 6-4-1. Different MCU mode can be set by hardware selection on BS1 pins. The display panel only supports 4-wire SPI or 3-wire SPI interface mode.

Pin Name	Data/Comma	nd Interface	Control Signal		
Bus interface	SDA	SCL	CS#	D/C#	RES#
BS1=L 4-wire SPI	SDA	SCL	CS#	D/C#	RES#
BS1=H 3-wire SPI	SDA	SCL	CS#	L	RES#

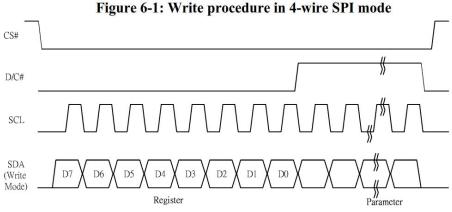
#### 6.3.2 MCU Serial Interface (4-wire SPI)

The serial interface consists of serial clock SCL, serial data SDA, D/C#, CS#. This interface supports Write mode and Read mode.

Function	CS#	D/C#	SCL
Write command	L	L	<b>†</b>
Write data	L	Н	<b>↑</b>

**Note:** † stands for rising edge of signal

In the write mode SDA is shifted into an 8-bit shift register on every rising edge of SCL in the order of D7, D6, ... D0. The level of D/C# should be kept over the whole byte. The data byte in the shift register is written to the Graphic Display Data RAM /Data Byte register or command Byte register according to D/C# pin.



In the Read mode:

- 1. After driving CS# to low, MCU need to define the register to be read.
- 2. SDA is shifted into an 8-bit shift register on every rising edge of SCL in the order of D7, D6, ... D0 with D/C# keep low.
- 3. After SCL change to low for the last bit of register, D/C# need to drive to high.
- 4. SDA is shifted out an 8-bit data on every falling edge of SCL in the order of D7, D6, ... D0.
- 5. Depending on register type, more than 1 byte can be read out. After all byte are read, CS# need to drive to high to stop the read operation.

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(Read Mode

D/C#

SCL

Register

Register

Parameter

Write Mode)

D7

D6

D5

D4

D3

D2

D1

D0

W

Figure 6-2: Read procedure in 4-wire SPI mode

#### 6.3.3 MCU Serial Interface (3-wire SPI)

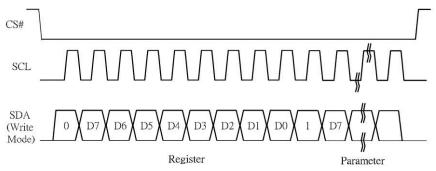
The 3-wire serial interface consists of serial clock SCL, serial data SDA and CS#. This interface also supports Write mode and Read mode.

The operation is similar to 4-wire serial interface while D/C# pin is not used. There are altogether 9-bits will be shifted into the shift register on every ninth clock in sequence: D/C# bit, D7 to D0 bit. The D/C# bit (first bit of the sequential data) will determine the following data byte in the shift register is written to the Display Data RAM (D/C# bit = 1) or the command register (D/C# bit = 0).

Function	CS#	D/C#	SCL
Write command	L	Tie	<b>†</b>
Write data	L	Tie	<b>†</b>

**Note**: † stands for rising edge of signal

Figure 6-3: Write procedure in 3-wire SPI mode



#### In the Read mode:

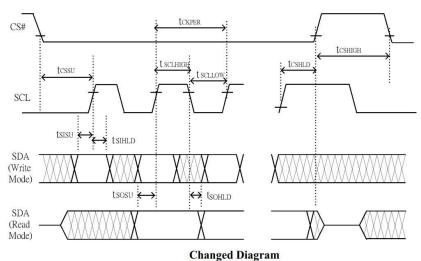
- 1. After driving CS# to low, MCU need to define the register to be read.
- 2. D/C=0 is shifted thru SDA with one rising edge of SCL
- 3. SDA is shifted into an 8-bit shift register on every rising edge of SCL in the order of D7, D6, ... D0.
- 4. D/C=1 is shifted thru SDA with one rising edge of SCL
- 5. SDA is shifted out an 8-bit data on every falling edge of SCL in the order of D7, D6, ... D0.
- 6. Depending on register type, more than 1 byte can be read out. After all byte are read, CS# need to drive to high to stop the read operation.

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Figure 6-4: Read procedure in 3-wire SPI mode

## **6.3.4 Interface Timing**

The following specifications apply for: VSS=0V, VCI=3.0V, TOPR =25°C.



#### **Serial Interface Timing Characteristics**

 $(VCI - VSS = 2.2V \text{ to } 3.7V, TOPR = 25^{\circ}C, CL=20pF)$ 

#### Write mode

Symbol	Parameter	Min	Тур	Max	Unit
f <sub>SCL</sub>	SCL frequency (Write Mode)			20	MHz
tcssu	Time CS# has to be low before the first rising edge of SCLK	60			ns
tcsHLD	Time CS# has to remain low after the last falling edge of SCLK	65			ns
tcsнigh	Time CS# has to remain high between two transfers	100			ns
tschigh	Part of the clock period where SCL has to remain high	25			ns
tscLLow	Part of the clock period where SCL has to remain low	25			ns
tsisu	Time SI (SDA Write Mode) has to be stable before the next rising edge of SCL	10			ns
tsihld	Time SI (SDA Write Mode) has to remain stable after the rising edge of SCL	40			ns

#### Read mode

Symbol	Parameter	Min	Тур	Max	Unit
fscL	SCL frequency (Read Mode)			2.5	MHz
tcssu	Time CS# has to be low before the first rising edge of SCLK	100		<i>I</i>	ns
tcshld	Time CS# has to remain low after the last falling edge of SCLK	50			ns
t <sub>csніgн</sub>	Time CS# has to remain high between two transfers	250			ns
tsclhigh	Part of the clock period where SCL has to remain high	180			ns
tscllow	Part of the clock period where SCL has to remain low	180			ns
tsosu	Time SO(SDA Read Mode) will be stable before the next rising edge of SCL		50	11/2	ns
tsohld	Time SO (SDA Read Mode) will remain stable after the falling edge of SCL		0		ns

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# 7. Command Table

WOUNDER		d Tal	Taxan San			I managed	4.00		100000	1	1	1	Land Control		
/W#	D/C#		D7	D6	D5	D4	D3	D2	D1	D0	Command	Descripti			
0	0	01	0	0	0	0	0	0	0	1	Driver Output control	Gate setti			.,
0	1		A <sub>7</sub>	$A_6$	<b>A</b> <sub>5</sub>	A <sub>4</sub>	Аз	A <sub>2</sub>	A <sub>1</sub>	Ao		A[8:0]= 12		], 296 MU tting as (A	
0	1		0	0	0	0	0	0	0	A <sub>8</sub>		WOX Gate	e illies se	ung as (A	[0.0] + 1).
0	1		0	0	0	0	0	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>		B[2]: GD Selects th GD=0 [PC G0 is the output sec GD=1, G1 is the output sec H[1]: SM Change s SM=0 [PC G0, G1, G interlaced SM=1, G0, G2, G B[0]: TB TB = 0 [PC	nning sequence is the canning of the	out Gate output cha G0,G1, G output cha G1, G0, G order of ga e95 (left ar	nnel, gate 2, G3, nnel, gate 33, G2, te driver. nd right ga
0	0	03	0	0	0	0	0	0	1	1	Gate Driving voltage	Set Gate			
0	1		0	0	0	<b>A</b> <sub>4</sub>	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	Ao	Control	A[4:0] = 0		0V to 20V	
												A[4:0]	VGH	A[4:0]	VGH
												00h	20	0Dh	15
												03h	10	0Eh	15.5
												04h	10.5	0Fh	16
												05h	11		16.5
														10h	
												06h	11.5	11h	17
												07h	12	12h	17.5
												08h	12.5	13h	18
												07h	12	14h	18.5
												08h	12.5	15h	19
												09h	13	16h	19.5
												0Ah	13.5	17h	20
												0Bh	14	Other	NA

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		Hex	D7	D6	D5	D4	D3	D2	D1	D0	Command	Description
0	0	04	0	0	0	0	0	1	0	0	Source Driving voltage	Set Source driving voltage
0	1		<b>A</b> <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	Аз	A <sub>2</sub>	A <sub>1</sub>	Ao	Control	A[7:0] = 41h [POR], VSH1 at 15V
0	1		B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	Вз	B <sub>2</sub>	B <sub>1</sub>	Bo	1	B[7:0] = A8h [POR], VSH2 at 5V. C[7:0] = 32h [POR], VSL at -15V
0	1		C <sub>7</sub>	C <sub>6</sub>	C <sub>5</sub>	C <sub>4</sub>	Сз	C <sub>2</sub>	C <sub>1</sub>	Co	1	Remark: VSH1>=VSH2

A/B[7:0]	VSH1/VSH2	A/B[7:0]	VSH1/VSH2		
8Eh	2.4	AFh	5.7		
8Fh	2.5	B0h	5.8		
90h	2.6	B1h	5.9		
91h	2.7	B2h	6		
92h	2.8	B3h	6.1		
93h	2.9	B4h	6.2		
94h	3	Boh	6.3		
95h	3.1	B6h	6.4		
96h	3.2	B7h	6.5		
97h	3.3	B8h	6.6		
98h	3.4	B9h	6.7		
99h	3.5	BAh	6.8		
9Ah	3.6	BBh	6.9		
9Bh	3.7	BCh	7		
9Ch	3.8	BDh	7.1		
9Dh	3.9	BEh	7.2		
9Eh	4	BFh	7.3		
9Fh	4.1	COh	7.4		
A0h	4.2	C1h	7.5		
A1h	4.3	C2h	7.6		
A2h	4.4	C3h	7.7		
A3h	4.5	C4h	7.8		
A4h	4.6	C5h	7.9		
A5h	4.7	C6h	8		
A6h	4.8	C7h	8.1		
A7h	4.9	C8h	8.2		
A8h	5	C9h	8.3		
A9h	5.1	CAh	8.4		
AAh	5.2	CBh	8.5		
ABh	5.3	CCh	8.6		
ACh	5.4	CDh	8.7		
ADh	5.5	CEh	8.8		
AEh	5.6	Other	NA		

to 17V

A/B[7:0]	VSH1/VSH2	A/B[7:0]	VSH1/VSH2
23h	9	3Ch	14
24h	9.2	3Dh	14.2
25h	9.4	3Eh	14.4
26h	9.6	3Fh	14.6
27h	9.8	40h	14.8
28h	10	41h	15
29h	10.2	42h	15.2
2Ah	10.4	43h	15.4
2Bh	10.6	44h	15.6
2Ch	10.8	45h	15.8
2Dh	11	46h	16
2Eh	11.2	47h	16.2
2Fh	11.4	48h	16.4
30h	11.6	49h	16.6
31h	11.8	4Ah	16.8
32h	12	4Bh	17
33h	12.2	Other	NA
34h	12.4		
35h	12.6		
36h	12.8		
37h	13		
38h	13.2		
39h	13.4		
3Ah	13.6		
3Bh	13.8		

C[7:0]	VSL		
0Ah	-5		
0Ch	-5.5		
0Eh	-6		
10h	-6.5		
12h	-7		
14h	-7.5		
16h	-8		
18h	-8.5		
1Ah	-9		
1Ch	-9.5		
1Eh	-10		
20h	-10.5		
22h	-11		
24h	-11.5		
26h	-12		
28h	-12.5		
2Ah	-13		
2Ch	-13.5		
2Eh	-14		
30h	-14.5		
32h	-15		
34h	-15.5		
36h	-16		
38h	-16.5		
3Ah	-17		
Other	NA		

0	0	08	0	0	0	0	1	0	0	0	Initial Code Setting OTP Program	Program Initial Code Setting
												The command required CLKEN=1. Refer to Register 0x22 for detail. BUSY pad will output high during operation.
•		00	0	•	•	•		•	•			N
0	0	09	0	0	0	0	1	0	0	1		Write Register for Initial Code Setting
0	1		A <sub>7</sub>	$A_6$	$A_5$	A <sub>4</sub>	Аз	$A_2$	A <sub>1</sub>	A <sub>0</sub>	Code Setting	Selection
0	1		B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	Вз	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>		A[7:0] ~ D[7:0]: Reserved Details refer to Application Notes of Initial
0	1		C <sub>7</sub>	C <sub>6</sub>	C <sub>5</sub>	C <sub>4</sub>	C <sub>3</sub>	C <sub>2</sub>	C <sub>1</sub>	Co		Code Setting
0	1		D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	Do		
0	0	0A	0	0	0	0	1	0	1	0	Read Register for Initial Code Setting	Read Register for Initial Code Setting

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/W#	D/C#	Hex	D7	D6	D5	D4	D3	D2	D1	D0	Command	Description				
0	0	0C	0	0	0	0	1	1	0	0	Booster Soft start	Booster Enable with Phase 1, Phase 2 and Phase				
0	1	-	1	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>	Control	for soft start current and duration setting.				
0	1		1	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	Bo	Control of the second	A[7:0] -> Soft start setting for Phase1				
0	1		1	C <sub>6</sub>	C <sub>5</sub>	C <sub>4</sub>	C <sub>3</sub>	C <sub>2</sub>	_	Co	_	= 8Bh [POR] B[7:0] -> Soft start setting for Phase2				
0	1		0	0	10000	-			-	-	-	= 9Ch [POR]				
U	4		U	U	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>		C[7:0] -> Soft start setting for Phase3 = 96h [POR]				
												D[7:0] -> Duration setting				
												= 0Fh [POR]				
												Bit Description of each byte: A[6:0] / B[6:0] / C[6:0]:				
												Bit[6:4] Driving Strength Selection				
												000 1(Weakest)				
												001 2				
												010 3				
												011 4				
												100 5				
												101 6				
												110 7				
												111 8(Strongest)				
												Bit[3:0] Min Off Time Setting of GDR				
												[ Time unit ]				
												NA NA				
												0011 0100 2.6				
												0101 3.2				
												0110 3.9				
												0111 4.6				
												1000 5.4				
												1001 6.3				
												1010 7.3				
												1011 8.4				
												1100 9.8				
												1101 11.5				
												1110 13.8				
												1111 16.5				
												D[5:0]: duration setting of phase D[5:4]: duration setting of phase 3 D[3:2]: duration setting of phase 2 D[1:0]: duration setting of phase 1  Bit[1:0]  Duration of Phase [Approximation]				
												00 10ms				
												01 20ms				
												10 30ms				
												11 40ms				
0	0	10	0	0	0	1	0	0	0	0 [	Deep Sleep mode	Deep Sleep mode Control:				
0	1		0	0	0	0	0	0	A <sub>1</sub>	Ao	138 Maria	A[1:0]: Description				
												00 Normal Mode [POR]				
												01 Enter Deep Sleep Mode 1				
												11 Enter Deep Sleep Mode 2				
												After this command initiated, the chip will enter Deep Sleep Mode, BUSY pad will keep output high. Remark: To Exit Deep Sleep mode, User required				
	ı		- 1			- 1						TO EXIL Deep Sleep mode. User required				



0	0	11	0	0	0	1	0	0	0	1	Data Entry mode setting	Define data entry sequence
0	1		0	0	0	0	0	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>	optimized at the committee of the commit	A[2:0] = 011 [POR]
												A [1:0] = ID[1:0] Address automatic increment / decrement setting The setting of incrementing or decrementing of the address counter can be made independently in each upper and lower bit of the address. 00 -Y decrement, X decrement, 01 -Y decrement, X increment, 10 -Y increment, X increment [POR]  A[2] = AM Set the direction in which the address counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR]  AM = 1, the address counter is updated in the Y direction.
0	0	12	0	0	0	1	0	0	1	0	SW RESET	It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode  During operation, BUSY pad will output high.  Note: RAM are unaffected by this command.
0	0	14	0	0	0	1	0	1	0	0	HV Ready Detection	HV ready detection A[7:0] = 00h [POR] The command required CLKEN=1 and ANALOGEN=1. Refer to Register 0x22 for detail. After this command initiated, HV Ready detection starts. BUSY pad will output high during detection. The detection result can be read from the Status Bit Read (Command 0x2F).
0	1		0	A <sub>6</sub>	A <sub>5</sub>	A4	0	A <sub>2</sub>	A <sub>1</sub>	Ao		A[6:4]=n for cool down duration: 10ms x (n+1) A[2:0]=m for number of Cool Down Loop to detect. The max HV ready duration is 10ms x (n+1) x (m) HV ready detection will be trigger after each cool down time. The detection will be completed when HV is ready. For 1 shot HV ready detection, A[7:0] can be set as 00h.



0	0	15	0	0	0	1	0	1	0	1	VCI Detection	VCI Detection
0	1	10	0	0	0	0	0	A <sub>2</sub>	A <sub>1</sub>	Ao	VOI Detection	A[2:0] = 100 [POR] , Detect level at 2.3V
	'							1.72	7 (1	/ 10		A[2:0] : VCI level Detect
												A[2:0] VCI level
												011 2.2V
												100 2.3V 101 2.4V
												101 2.4V 110 2.5V
												110 2.5V 111 2.6V
												Other NA
												The command required CLKEN=1 and
												ANALOGEN=1
												Refer to Register 0x22 for detail.
												After this command initiated VOI
												After this command initiated, VCI detection starts.
												BUSY pad will output high during
												detection.
												The detection result can be read from the Status Bit Read (Command 0x2F).
											<u> </u>	Status Dit Nead (Command OAZI ).
0	0	18	0	0	0	1	1	0	0	0	Temperature Sensor	Temperature Sensor Selection
0	1		A <sub>7</sub>	A <sub>6</sub>	<b>A</b> <sub>5</sub>	A <sub>4</sub>	Аз	$A_2$	A <sub>1</sub>	A <sub>0</sub>	Control	A[7:0] = 48h [POR], external temperatrure sensor
												A[7:0] = 80h Internal temperature sensor
				9		0 000	50 0		E 1500			
0	0	1A	0	0	0	1	1	0	1	0	Temperature Sensor Control (Write to	Write to temperature register. A[11:0] = 7FFh [POR]
0	1		A <sub>11</sub>	A <sub>10</sub>	<b>A</b> 9	A <sub>8</sub>	A <sub>7</sub>	<b>A</b> <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	temperature register)	A[TI.0] = TEFIT [FOR]
0	1		Аз	A <sub>2</sub>	A <sub>1</sub>	Ao	0	0	0	0	J,	
0	0	1B	0	0	0	1	1	0	1	1	Temperature Sensor	Read from temperature register.
1	1	1000000	A <sub>11</sub>	A <sub>10</sub>	A <sub>9</sub>	A <sub>8</sub>	A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A4	Control (Read from	
1	1		A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	Ao	0	0	0	0	temperature register)	
0	0	1C	0	0	0	1	1	1	0	0	Temperature Sensor	Write Command to External temperature
0	1	10	A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	Ao	Control (Write Command	sensor.
0	1		B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	Bo	to External temperature	A[7:0] = 00h [POR],
0	1		C <sub>7</sub>	C <sub>6</sub>	C <sub>5</sub>	C <sub>4</sub>	C <sub>3</sub>	C <sub>2</sub>	C <sub>1</sub>	Co	sensor)	B[7:0] = 00h [POR], C[7:0] = 00h [POR],
	58			-0			-0					
												A[7:6]
												A[7:6] Select no of byte to be sent 00 Address + pointer
												01 Address + pointer + 1st parameter
												10 Address + pointer + 1st parameter + 2nd pointer
												11 Address
												A[5:0] – Pointer Setting B[7:0] – 1st parameter
												C[7:0] – 1 <sup>th</sup> parameter
												The command required CLKEN=1.
												Refer to Register 0x22 for detail.
												After this command initiated, Write
												Command to external temperature sensor
												starts. BUSY pad will output high during
												operation.
0	0	20	0	0	1	0	0	0	0	0	Master Activation	Activate Display Update Sequence
											111	The Display Undate Sequence Option is
												The Display Update Sequence Option is located at R22h.
												BUSY pad will output high during
												operation. User should not interrupt this
												operation to avoid corruption of panel images.
												9-5.

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0	0	21	0	0	1	0	0	0	0	1	Display Update Control	RAM content option for Display Upda	ite
0	1		A <sub>7</sub>	<b>A</b> <sub>6</sub>	<b>A</b> <sub>5</sub>	A <sub>4</sub>	<b>A</b> <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>	1	A[7:0] = 00h [POR] B[7:0] = 00h [POR]	
0	1		В7	0	0	0	0	0	0	0		A[7:4] Red RAM option         0000       Normal         0100       Bypass RAM content at a loop         1000       Inverse RAM content         A[3:0] BW RAM option         0000       Normal         0100       Bypass RAM content at a loop         1000       Inverse RAM content	
												B[7] Source Output Mode  O Available Source from S0 to S  Available Source from S8 to S	
0	1	22	0 A <sub>7</sub>	0 A <sub>6</sub>	1 A <sub>5</sub>	0 A <sub>4</sub>	0 A <sub>3</sub>	0 A <sub>2</sub>	1 A <sub>1</sub>	0 A <sub>0</sub>	Display Update Control 2	Display Update Sequence Option: Enable the stage for Master Activatio A[7:0]= FFh (POR)	n
												Operating sequence Parar	lex)
												Enable clock signal 8 Disable clock signal 0	
												Enable clock signal	0
												→ Enable Analog  Disable Analog  → Disable clock signal	3
												Enable clock signal  → Load LUT with DISPLAY Mode 1  → Disable clock signal	1
												Enable clock signal  → Load LUT with DISPLAY Mode 2  → Disable clock signal	9
												Enable clock signal  → Load temperature value  → Load LUT with DISPLAY Mode 1  → Disable clock signal	1
												Enable clock signal  → Load temperature value  → Load LUT with DISPLAY Mode 2  → Disable clock signal	9
												Enable clock signal  → Enable Analog  → Display with DISPLAY Mode 1  → Disable Analog  → Disable OSC	7
												Enable clock signal → Enable Analog → Display with DISPLAY Mode 2 → Disable Analog → Disable OSC	F
												Enable clock signal →Enable Analog → Load temperature value → DISPLAY with DISPLAY Mode 1 → Disable Analog → Disable OSC	7
												Enable clock signal → Enable Analog → Load temperature value → DISPLAY with DISPLAY Mode 2 → Disable Analog → Disable OSC	F
0	0	24	0	0	1	0	0	1	0	0	Write RAM (Black White) / RAM 0x24	written into the BW RAM until anothe command is written. Address pointers advance accordingly	r
												For Write pixel: Content of Write RAM(BW) = 1 For Black pixel: Content of Write RAM(BW) = 0	

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_	man		The state of the state of			1000		-				
/W#	D/C#		D7	D6	D5	D4	D3	D2	D1	D0	Command	Description
0	0	26	0	0	1	0	0	1	1	0	Write RAM (RED) / RAM 0x26	After this command, data entries will be written into the RED RAM until another command is written. Address pointers will advance accordingly.
												For Red pixel: Content of Write RAM(RED) = 1 For non-Red pixel [Black or White]: Content of Write RAM(RED) = 0
0	0	27	0	0	1	0	0	1	1	1	Read RAM	After this command, data read on the MCU bus will fetch data from RAM. According to parameter of Register 41h to select reading RAM0x24/ RAM0x26, until another command is written. Address pointers will advance accordingly.  The 1st byte of data read is dummy data.
0	0	28	0	0	1	0	1	0	0	0	VCOM Sense	Enter VCOM sensing conditions and hold for duration defined in 29h before reading VCOM value. The sensed VCOM voltage is stored in register The command required CLKEN=1 and ANALOGEN=1 Refer to Register 0x22 for detail.
												BUSY pad will output high during operation.
										,		1
0	0	29	0	0	1	0	1	0	0	1	VCOM Sense Duration	Stabling time between entering VCOM sensing mode and reading acquired.
0	1		0	1	0	0	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	Ao		A[3:0] = 9h, duration = 10s. VCOM sense duration = (A[3:0]+1) sec
0	0	2A	0	0	1	0	1	0	1	0	Program VCOM OTP	Program VCOM register into OTP
												The command required CLKEN=1. Refer to Register 0x22 for detail.
												BUSY pad will output high during operation.
0	0	2B	0	0	1	0	1	0	1	1	Write Register for VCOM	This command is used to reduce glitch
0	1	20	0	0	0	0	0	1	0	0	Control	when ACVCOM toggle. Two data bytes
0	1	ş: )	0	1	1	0	0	0	1	1	Market Ma	D04h and D63h should be set for this command.

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Com	man	d Ta	ble													
	/W# D/C# Hex D7 D6 D5 D4 D3 D2 D1 D0 Command											Description				
0	0	2C	0	0	1	0	1	1	0	0	Write VCOM register			er from M	ICU interface	
0	1		A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	Ao			00h [POR]			
												A[7:0]	VCOM	A[7:0]	VCOM	
												08h	-0.2	44h	-1.7	
												0Ch	-0.3	48h	-1.8	
												10h	-0.4	4Ch	-1.9	
												14h	-0.5	50h	-2	
												18h	-0.6	54h	-2.1	
												1Ch	-0.7	58h	-2.2	
												20h	-0.8	5Ch	-2.3	
												24h	-0.9	60h	-2.4	
												28h	-1	64h	-2.5	
												2Ch 30h	-1.1 -1.2	68h 6Ch	-2.6	
															-2.7	
												34h 38h	-1.3 -1.4	70h 74h	-2.8 -2.9	
												3Ch	-1.4	74h	-2.9	
												40h	-1.5	Other	NA	
- di												4011	-1.0	Other	INA	
0	0	2D	0	0	1	0	1	1	0	1	OTP Register Read for	Pood F	Register for	Dienlay (	Ontion:	
1	1	20	A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	Ao	Display Option	i leau r	cyloler IUI	Display (	οριίοπ.	
1	1		B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>			VCOM OT		on	
- 0 - 6			-		_	_		-				(Comm	and 0x37,	Byte A)		
1	1		C <sub>7</sub>	C <sub>6</sub>	C <sub>5</sub>	C <sub>4</sub>	C <sub>3</sub>	C <sub>2</sub>	C <sub>1</sub>	C <sub>0</sub>		D[7.0]	VOON D			
1	1		D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>			VCOM Reg and 0x2C)			
1	1		E <sub>7</sub>	E <sub>6</sub>	E <sub>5</sub>	E <sub>4</sub>	E <sub>3</sub>	E <sub>2</sub>	E <sub>1</sub>	Εo		(001111	iana uzzu)			
1	1		F <sub>7</sub>	F <sub>6</sub>	F <sub>5</sub>	F <sub>4</sub>	F <sub>3</sub>	F <sub>2</sub>	F <sub>1</sub>	Fo		C[7:0]~	·G[7:0]: Dis	play Mod	le	
1	1		G <sub>7</sub>	G <sub>6</sub>	G <sub>5</sub>	G <sub>4</sub>	G <sub>3</sub>	G <sub>2</sub>	G <sub>1</sub>	G <sub>0</sub>			and 0x37,	Byte B to	Byte F)	
1	1		H <sub>7</sub>	H <sub>6</sub>	H <sub>5</sub>	H <sub>4</sub>	Нз	H <sub>2</sub>	H <sub>1</sub>	Ho		[5 byte:	s]			
1	1		17	16	15	14	l <sub>3</sub>	12	l <sub>1</sub>	I <sub>0</sub>		H[7:0]~K[7:0]: Waveform Version (Command 0x37, Byte G to Byte J) [4 bytes]				
1	1		J <sub>7</sub>	J <sub>6</sub>	<b>J</b> <sub>5</sub>	J <sub>4</sub>	Jз	J <sub>2</sub>	J <sub>1</sub>	Jo						
1	1		K <sub>7</sub>	K <sub>6</sub>	K <sub>5</sub>	K <sub>4</sub>	K <sub>3</sub>	K <sub>2</sub>	K <sub>1</sub>	K <sub>0</sub>						
•					0			2	• • •	0						
0	0	2E	0	0	1	0	1	1	1	0	User ID Read	Read 10	Byte User	ID store	ed in OTP:	
1	1		A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A4	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	Ao		A[7:0]]~	J[7:0]: User		Byte A and	
1	1		B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	Вз	B <sub>2</sub>	Bı	Bo		Byte J)	[10 bytes]			
1	1		C <sub>7</sub>	C <sub>6</sub>	C <sub>5</sub>	C <sub>4</sub>	C <sub>3</sub>	C <sub>2</sub>	C <sub>1</sub>	Co						
1	1		D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>							
	-		-		-		-	100000000000000000000000000000000000000		-						
1	1		E <sub>7</sub>	E <sub>6</sub>	E <sub>5</sub>	E <sub>4</sub>	E <sub>3</sub>	E <sub>2</sub>	E <sub>1</sub>	E <sub>0</sub>						
1	1		F <sub>7</sub>	F <sub>6</sub>	F <sub>5</sub>	F <sub>4</sub>	F <sub>3</sub>	F <sub>2</sub>	F <sub>1</sub>	Fo						
1	1		G <sub>7</sub>	G <sub>6</sub>	G <sub>5</sub>	G <sub>4</sub>	G <sub>3</sub>	G <sub>2</sub>	G <sub>1</sub>	G <sub>0</sub>						
1	1		H <sub>7</sub>	H <sub>6</sub>	H <sub>5</sub>	H <sub>4</sub>	H <sub>3</sub>	H <sub>2</sub>	H <sub>1</sub>	H₀						
1	1		17	16	15	14	l <sub>3</sub>	12	l <sub>1</sub>	lo						
1	1		J <sub>7</sub>	J <sub>6</sub>	<b>J</b> <sub>5</sub>	J <sub>4</sub>	Jз	J <sub>2</sub>	J <sub>1</sub>	J <sub>0</sub>						
0	0	2F	0	0	1	0	1	1	1	1	Status Bit Read	Read IC	status Bit [	POR 0x0	01]	
1	1		0	0	A <sub>5</sub>	A <sub>4</sub>	0	0	A <sub>1</sub>	Ao		A[5]: HV	Ready Det		g [POR=0]	
0.50									3.34			0: Ready				
												1: Not R	eady	fl (DO	D-01	
												0: Norma	I Detection	nag [PO	R=UJ	
													wer than th	e Detect	level	
												A[3]: [PC			.0.0.	
													sy flag [POI	R=0]		
												0: Norma				
												1: BUSY		D=041		
												A[1:0]: C	hip ID [POI	K-01]		
												Remark:				
													A[4] status			
													they need			
												respectiv	d 0x14 and	comma	nd UX15	
												respectiv	ely.			



0	0	30	0	0	1	1	0	0	0	0	Program WS OTP	Program OTP of Waveform Setting The contents should be written into RAM before sending this command.  The command required CLKEN=1. Refer to Register 0x22 for detail. BUSY pad will output high during operation.
0	0	31	0	0	1	1	0	0	0	1	Load WS OTP	Load OTP of Waveform Setting  The command required CLKEN=1. Refer to Register 0x22 for detail.  BUSY pad will output high during operation.
0	0	32	0	0	1	1	0	0	1	0	Write LUT register	Write LUT register from MCU interface
0	1		<b>A</b> <sub>7</sub>	<b>A</b> <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	<b>A</b> <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	Ao		[153 bytes], which contains the content of VS[nX-LUTm], TP[nX], RP[n], SR[nXY],
0	1		B <sub>7</sub>	B₀	Во	B <sub>4</sub>	Вз	B <sub>2</sub>	В	Bo		FR[n] and XON[nXY]
0	1		7.5	- \$	•		-			1		Refer to Session 6.7 WAVEFORM SETTING
-	1		•	••	•	•	•	•				OLITING .
0	0	34	0	0	1	1	0	1	0	0	CRC calculation	CRC calculation command For details, please refer to SSD1680 application note.  BUSY pad will output high during
		g			g.							operation.
0	0	35	0	0	1	1	0	1	0	1	CRC Status Read	CRC Status Read
1	1		A <sub>15</sub>	A <sub>14</sub>	A <sub>13</sub>	A <sub>12</sub>	A <sub>11</sub>	A <sub>10</sub>	A <sub>9</sub>	A <sub>8</sub>		A[15:0] is the CRC read out value
1	1		A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	<b>A</b> <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>		
0	0	36	0	0	1	1	0	1	1	0	Program OTP selection	Program OTP Selection according to the OTP Selection Control [R37h and R38h]  The command required CLKEN=1. Refer to Register 0x22 for detail. BUSY pad will output high during operation.
0	0	37	0	0	1	1	0	1	1	1	Write Register for Display	Write Register for Display Option
0	1		A <sub>7</sub>	0	0	0	0	0	0	0	Option	A[7] Spare VCOM OTP selection
0	1		В	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	Вз	B <sub>2</sub>	B <sub>1</sub>	Bo		0: Default [POR] 1: Spare
0	1		C <sub>7</sub>	C <sub>6</sub>	C <sub>5</sub>	C <sub>4</sub>	C <sub>3</sub>	C <sub>2</sub>	C <sub>1</sub>	C <sub>0</sub>		B[7:0] Display Mode for WS[7:0]
0	1		D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>		C[7:0] Display Mode for WS[15:8]
0	1		0	F <sub>6</sub>	0	0	F <sub>3</sub>	F <sub>2</sub>	F <sub>1</sub>	Fo		D[7:0] Display Mode for WS[23:16] E[7:0] Display Mode for WS[31:24]
0	1		G <sub>7</sub>	G <sub>6</sub>	G <sub>5</sub>	G <sub>4</sub>	G <sub>3</sub>	G <sub>2</sub>	G <sub>1</sub>	G <sub>0</sub>		F[3:0 Display Mode for WS[35:32]
0	1		H <sub>7</sub>	H <sub>6</sub>	H <sub>5</sub>	H <sub>4</sub>	Нз	H <sub>2</sub>	H <sub>1</sub>	Ho		0: Display Mode 1 1: Display Mode 2
0	1		l <sub>7</sub>	<b>I</b> 6	15	14	<b>l</b> <sub>3</sub>	12	11	l <sub>o</sub>		Statement with the Statement of the Stat
0	1		J <sub>7</sub>	J <sub>6</sub>	<b>J</b> 5	J <sub>4</sub>	J <sub>3</sub>	$J_2$	J <sub>1</sub>	Jo		F[6]: PingPong for Display Mode 2 0: RAM Ping-Pong disable [POR] 1: RAM Ping-Pong enable G[7:0]~J[7:0] module ID /waveform version.

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0	0	38	0	0	1	1	1	0	0	0	Write Register for User ID	Write Register for User ID
0	1	00	A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	Ao	TTILL TROUBLES TO COSET ID	A[7:0]]~J[7:0]: UserID [10 bytes]
0	1		B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	Вз	B <sub>2</sub>	B <sub>1</sub>	Bo		Remarks: A[7:0]~J[7:0] can be stored in
0	1		C <sub>7</sub>	C <sub>6</sub>	C <sub>5</sub>	C <sub>4</sub>	C <sub>3</sub>	C <sub>2</sub>	C <sub>1</sub>	Co		OTP
0	1		D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>		
0	1		E <sub>7</sub>	E <sub>6</sub>	E <sub>5</sub>	E <sub>4</sub>	E <sub>3</sub>	E <sub>2</sub>	E <sub>1</sub>	E <sub>0</sub>		
0	1		F <sub>7</sub>	F <sub>6</sub>	F <sub>5</sub>	F <sub>4</sub>	F₃ G₃	F <sub>2</sub>	F <sub>1</sub>	F <sub>0</sub>		
0	1		H <sub>7</sub>	H <sub>6</sub>	H <sub>5</sub>	H <sub>4</sub>	H <sub>3</sub>	H <sub>2</sub>	H <sub>1</sub>	H <sub>0</sub>		
0	1		17	16	15	14	l <sub>3</sub>	12	11	lo		
0	1		J <sub>7</sub>	J <sub>6</sub>	J <sub>5</sub>	J <sub>4</sub>	J <sub>3</sub>	J <sub>2</sub>	J <sub>1</sub>	Jo		
											i zez	
0	1	39	0	0	0	0	0	0	0 A <sub>1</sub>	1 A <sub>0</sub>	OTP program mode	OTP program mode A[1:0] = 00: Normal Mode [POR] A[1:0] = 11: Internal generated OTP programming voltage  Remark: User is required to EXACTLY follow the reference code sequences
0	0	3C	0	0	1	1	1	1	0	0	Border Waveform Control	Select border waveform for VBD
0	1	55	A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	0	A <sub>2</sub>	A <sub>1</sub>	Ao	251461 Travoloilli Golilloi	A[7:0] = C0h [POR], set VBD as HIZ.
9767			55,036			15 (1575	1000		55656			A [7:6] :Select VBD option
												A[7:6] Select VBD as 00 GS Transition,
												Defined in A[2] and
												A[1:0]
												01 Fix Level,
												Defined in A[5:4] 10 VCOM
												11[POR] HiZ
												A [5:4] Fix Level Setting for VBD A[5:4] VBD level
												00 VSS
												01 VSH1
												10 VSL
												11 VSH2
												A[2] GS Transition control
												A[2] GS Transition control
												0 Follow LUT
												(Output VCOM @ RED)  1 Follow LUT
												1 Follow LOT
												A [1:0] GS Transition setting for VBD
												A[1:0] VBD Transition
												00 LUT0 01 LUT1
												10 LUT2
												11 LUT3
_	_	0-		_							E 10 " /====	lo ii c uu <del>u</del>
0	0	3F	0	0	1	1	1	1	1	1	End Option (EOPT)	Option for LUT end A[7:0]= 02h [POR]
0	1		A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	Аз	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>		22h Normal.
												07h Source output level keep
												previous output before power off
0	0	41	0	1	0	0	0	0	0	1	Read RAM Option	Read RAM Option
0	1	71	0	0	0	0	0	0	0	Ao	Acad Tolivi Option	A[0]= 0 [POR]
J			0	J		J	0	J		~10		0 : Read RAM corresponding to RAM0x24 1 : Read RAM corresponding to RAM0x26
0	0	44	0	1	0	0	0	1	0	0	Set RAM X - address	Specify the start/end positions of the
0	1		0	0	A <sub>5</sub>	A <sub>4</sub>	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	Ao	Start / End position	window address in the X direction by an
0	1		0	0	B <sub>5</sub>	B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	Bo		address unit for RAM
U			J	J	25	<b>J</b> 4	23	52		0		A[5:0]: XSA[5:0], XStart, POR = 00h B[5:0]: XEA[5:0], XEnd, POR = 15h
_						L						Dio.oj. ALAjo.oj, ALAu, 1 OK - 1011

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0	0	45	0	1	0	0	0	1	0	1	Set Ram Y- address	Specify the	e start/en	d position:	s of the
0	1		A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	<b>A</b> <sub>4</sub>	Аз	A <sub>2</sub>	A <sub>1</sub>	Ao	Start / End position				ction by an
0	1		0	0	0	0	0	0	0	A <sub>8</sub>		address u	IIILIOF KA	IVI .	
0	1		B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	Вз	B <sub>2</sub>	B <sub>1</sub>	Bo		A[8:0]: YS			
0	1		0	0	0	0	0	0	0	Вв		B[8:0]: YE			
0	0	46	0 A <sub>7</sub>	1 A <sub>6</sub>	0 A <sub>5</sub>	0 A <sub>4</sub>	0	1 A <sub>2</sub>	1 A <sub>1</sub>	0 A <sub>0</sub>	Auto Write RED RAM for Regular Pattern	Auto Write A[7:0] = 00		M for Reg	ular Patterr
U	3		A/	A6	As	A4	O	A2	Ai	Α0		A[7]: The 1st step value, POR = 0 A[6:4]: Step Height, POR= 000 Step of alter RAM in Y-direction according to Gate			
												A[6:4]	Height	A[6:4]	Height
												000	8	100	128
												001	16	101	256
												010	32	110	296
												011	64	111	NA
												A[2:0]: Ste Step of alt to Source			on accordin
												A[2:0]	Width	A[2:0]	Width
												000	8	100	128
												001	16	101	176
												010	32	110	NA
												011	64	111	NA
												BUSY pad operation.	will outpu	ut high du	ring
0	1	47	0 A <sub>7</sub>	1 A <sub>6</sub>	0 A <sub>5</sub>	0 A <sub>4</sub>	0	1 A <sub>2</sub>	1 A <sub>1</sub>	A <sub>o</sub>	Auto Write B/W RAM for Regular Pattern	Auto Write B/W RAM for Regular Pattern A[7:0] = 00h [POR]  A[7]: The 1st step value, POR = 0 A[6:4]: Step Height, POR= 000  Step of alter RAM in Y-direction according to Gate			
												A[6:4]	Height	A[6:4]	Height
												000	8	100	128
												001	16	101	256
												010	32	110	296
												011	64	111	NA
												to Source A[2:0] 000 001 010 011	Width 8 16 32 64	A[2:0] 100 101 110 111	Width 128 176 NA NA
	0	45	_	1			4	4	4		Cat DAM V address	During ope		N I II	
0	0	4E	0	1	0	0	1	1	1	0	Set RAM X address counter	Make initia address in			
0	1		0	0	A <sub>5</sub>	A <sub>4</sub>	Аз	A <sub>2</sub>	A <sub>1</sub>	Ao	- Country	A[5:0]: 00		oss courill	oi (AO)
	0	4F	0	1	0	0	1	1	1	1	Set RAM Y address	Make initia	al settinas	for the R	AM Y
0	8966	5581	A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>	counter	address in	the addre	ess count	er (AC)
(35)	1			2000	0	0	0	0	0	A <sub>8</sub>		A[8:0]: 000			
0	1		0	0	U										
0 0 0	100		0	0	0						NOP				

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# **8.Optical Specifications**

Measurements are made with that the illumination is under an angle of 45 degree, the detection is perpendicular unless otherwise specified

Symbol	Parameter	Conditions	Min	Typ.	Max	Units	Notes
R	White Reflectivity	White	30	35	-	%	8-1
CR	Contrast Ratio	Indoor	8:1		-		8-2
GN	2Grey Level	-		DS+(WS-DS)*n(m-1)			8-3
T update	Image update time	at 25 °C		3	-	sec	
Life		Topr		1000000times or 5years			

#### **Notes:**

8-1. Luminance meter: Eye-One Pro Spectrophotometer.

8-2. CR=Surface Reflectance with all white pixel/Surface Reflectance with all black pixels.

8-3 WS: White state, DS: Dark state

WINSTAR Display 25/37 2.9 inch Series



#### 9. Handling, Safety and Environment Requirements

#### Warning

The display glass may break when it is dropped or bumped on a hard surface. Handle with care. Should the display break, do not touch the electrophoretic material. In case of contact with electrophoretic material, wash with water and soap.

#### **Caution**

The display module should not be exposed to harmful gases, such as acid and alkali gases, which corrode electronic components. Disassembling the display module.

Disassembling the display module can cause permanent damage and invalidates the warranty agreements.

Observe general precautions that are common to handling delicate electronic components. The glass can break and front surfaces can easily be damaged. Moreover the display is sensitive to static electricity and other rough environmental conditions.

	Data sheet status
Product specification	This data sheet contains final product specifications.
	Limiting values

Limiting values given are in accordance with the Absolute Maximum Rating System (IEC134). Stress above one or more of the limiting values may cause per manent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

#### **Application information**

Where application information is given, it is advisory and does not form part of the specification.

WINSTAR Display 26/37 2.9 inch Series



# 10.Reliability test

NO	Test items	Test condition
1	Low-Temperature Storage	T = -25°C, 240 h Test in white pattern
2	High-Temperature Storage	T=70°C, RH=40%, 240h Test in white pattern
3	High-Temperature Operation	T=50°C, RH=35%, 240h
4	Low-Temperature Operation	0°C, 240h
5	High-Temperature, High-Humidity Operation	T=40°C, RH=80%, 240h
6	High Temperature, High Humidity Storage	T=50°C, RH=80%, 240h Test in white pattern
7	Temperature Cycle	1 cycle:[-25° C 30min]→[+70 ° C 30 min] : 50 cycles Test in white pattern
8	UV exposure Resistance	765W/m² for 168hrs,40 °C Test in white pattern
9	ESD Gun	Air+/-15KV;Contact+/-8KV (Test finished product shell, not display only) Air+/-8KV;Contact+/-6KV (Naked EPD display, no including IC and FPC area) Air+/-4KV;Contact+/-2KV (Naked EPD display, including IC and FPC area)

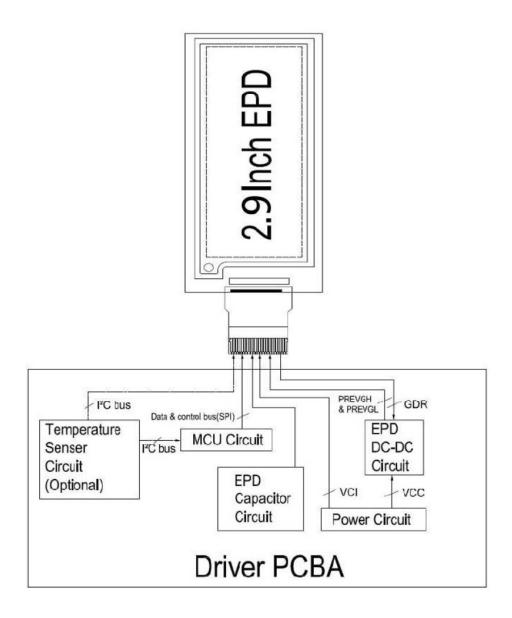
#### Note:

Put in normal temperature for 1hour after test finished, display performance is ok.

WINSTAR Display 27/37 2.9 inch Series



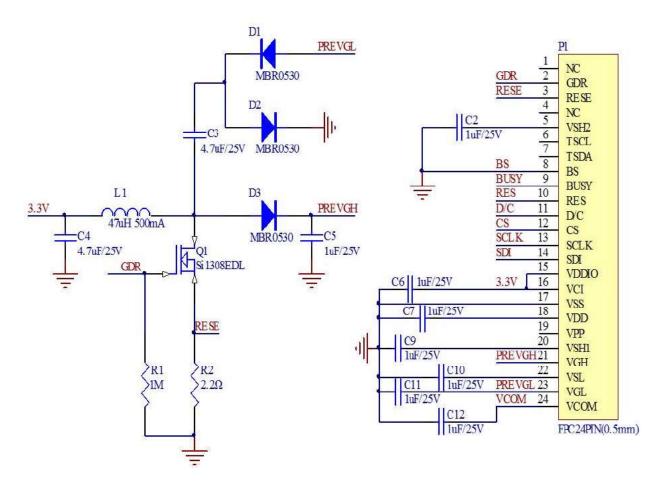
# 11. Block Diagram



WINSTAR Display 28/37 2.9 inch Series



#### 12. Reference Circuit



WINSTAR Display 29/37 2.9 inch Series



#### 13. Matched Development Kit

Our Development Kit designed for SPI E-paper Display aims to help users to learn how to use E-paper Display more easily. It can refresh black-white

E-paper Display and three-color (black, white and red/Yellow) WINSTAR Display 's E-paper Display. And it is also added the functions of USB serial port, Raspberry Pi and LED indicator light ect.

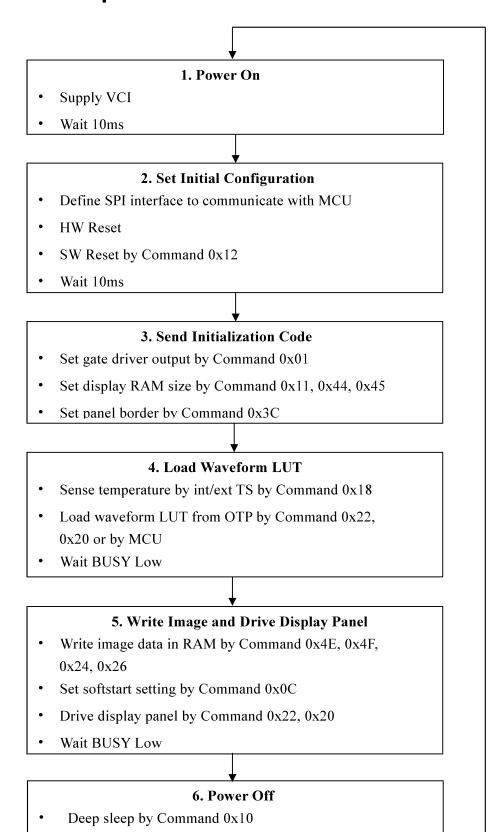
DESPI Development Kit consists of the development board and the pinboard.

WINSTAR Display 30/37 2.9 inch Series



## 14. Typical Operating Sequence

## 14.1 Normal Operation Flow



Power OFF



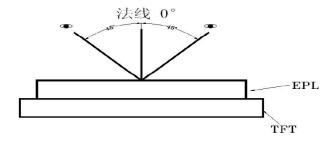
# 15.1 Environment

Temperature:  $25\pm3^{\circ}$ C Humidity:  $55\pm10^{\circ}$ RH

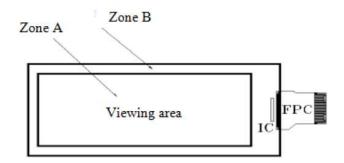
#### 15.2 Illuminance

 $Brightness: 1200 {\sim} 1500 LUX; distance: 20-30 CM; Angle: Relate~30° surround.$ 

# 15.3 Inspection method



# 15.4 Display area



WINSTAR Display 32/37 2.9 inch Series



# 15.5 Inspection standard

# 15.5.1 Electric inspection standard

NO.	Item	Standard	Defect level	Method	Scope
1	Display	Display complete Display uniform	MA		
2	Black/White spots	D≤0.25mm, Allowed 0.25mm < D≤0.4mm ∘ N≤3, and Distance≥5mm 0.4mm < D Not Allow	MI	Visual inspection	
3	Black/White spots (No switch)	L $\leq$ 0.6mm, W $\leq$ 0.2mm, N $\leq$ 1 L $\leq$ 2.0mm,W $>$ 0.2mm, Not Allow L $>$ 0.6mm, Not Allow		Visual/ Inspection card	Zone A
4	Ghost image	Allowed in switching process	MI	Visual inspection	
5	Flash spots/ Larger FPL size	Flash spots in switching, Allowed FPL size larger than viewing area, Allowed	MI	Visual/ Inspection card	Zone A Zone B
6	Display wrong/Missing	All appointed displays are showed correct	MA	Visual inspection	Zone A
7	Short circuit/ Circuit break/ Display abnormal	Not Allow		1.5	

WINSTAR Display 33/37 2.9 inch Series



# 15.5.2 Appearance inspection standard

NO.	Item	Standard	Defect level	Method	Scope
1	B/W spots /Bubble/ Foreign bodies/ Dents	D= $(L+W)/2$ D $\leq 0.25$ mm, Allowed 0.25mm $\leq D\leq 0.4$ mm, N $\leq 3$ D $\geq 0.4$ mm, Not Allow	MI	Visual inspection	Zone A
2	Glass crack	Not Allow	MA	Visual	Zone A Zone B
3	Dirty	Allowed if can be removed	MI	/ Microscope	Zone A Zone B
4	Chips/Scratch/ Edge crown	$X \le 3$ mm, $Y \le 0.5$ mmAnd without affecting the electrode is permissible $2$ mm $\le X$ or $2$ mm $\le Y$ Not Allow $W \le 0.1$ mm, $L \le 5$ mm, No harm to the electrodes and $N \le 2$ allow	MI	Visual / Microscope	Zone A Zone B
5	TFT Cracks	Not Allow	MA	Visual / Microscope	Zone A Zone B
6	Dirty/ foreign body	Allowed if can be removed/ allow	MI	Visual / Microscope	Zone A / Zone B
7	FPC broken/ Goldfingers exidation/ scratch	Not Allow	MA	Visual / Microscope	Zone B

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8	TFT edge bulge /TFT chromatic aberration	TFT edge bulge: $X \le 3$ mm, $Y \le 0.3$ mm Allowed TFT chromatic aberration :Allowed	MI	Visual / Microscope	Zone A Zone B
9	PCB damaged/ Poor welding/ Curl	PCB (Circuit area) damaged Not Allow PCB Poor welding Not Allow PCB Curl≤1%			
10	Edge glue height/ Edge glue bubble	Edge Adhesives H≤PS surface (Including protect film) Edge adhesives seep in≤1/2 Margin width Length excluding Edge adhesives bubble: bubble Width ≤1/2 Margin width; Length ≤0.5mm₀ n≤5	MI	Visual / Ruler	Zone B
11	Protect film	Surface scratch but not effect protect function, Allowed		Visual Inspection	
12	Silicon glue	Thickness ≤ PS surface(With protect film): Full cover the IC; Shape: The width on the FPC ≤ 0.5mm (Front) The width on the FPC ≤ 1.0mm (Back) smooth surface,No obvious raised.	MI	Visual Inspection	
13	Warp degree (TFT substrate)	t≤2.0mm	MI	Ruler	
14	Color difference in COM area (Silver point area)	Allowed		Visual Inspection	

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# 16. Packing

TBD



#### 17. Precautions

- (1) Do not apply pressure to the EPD panel in order to prevent damaging it.
- (2) Do not connect or disconnect the interface connector while the EPD panel is in operation.
- (3) Do not touch IC bonding area. It may scratch TFT lead or damage IC function.
- (4) Please be mindful of moisture to avoid its penetration into the EPD panel, which may cause damage during operation.
- (5) If the EPD Panel / Module is not refreshed every 24 hours, a phenomena known as "Ghosting" or "Image Sticking" may occur. It is recommended to refreshed the ESL /EPD Tag every 24 hours in use case. It is recommended that customer ships or stores the ESL / EPD Tag with a completely white image to avoid this issue
- (6) High temperature, high humidity, sunlight or fluorescent light may degrade the EPD panel's performance. Please do not expose the unprotected EPD panel to high temperature, high humidity, sunlight, or fluorescent for long periods of time.

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